

Physics 101H

General Physics 1 - Honors



Lecture 43 - 11/17/23

SHM and Circular Motion



Summary

Topics

Yesterday: Oscillations [[chapter 15](#)]

- Mass on a spring
- Simple harmonic motion

Today: Oscillations [[chapter 15](#)]

- SHM and uniform circular motion

Announcements

Next week:

Lectures posted to Blackboard

Simple harmonic motion



Key quantities:

- Amplitude
- Frequency
- Period
- Phase
- Velocity
- Maximum velocity
- Acceleration
- Maximum acceleration

Harmonic motion



Uniform circular motion (projected onto a single axis) is secretly simple harmonic motion

This projection actually helps us understand Euler's formula!

In fact, "everything is a harmonic oscillator"

Example 43.1: Show that a simple pendulum, in the small angle approximation, undergoes simple harmonic motion.



Summary

Topics

Today: Oscillations [[chapter 15](#)]

- SHM and uniform circular motion

“Monday”: Oscillations [[chapter 16](#)]

- Damped oscillations
- Forced oscillations

Announcements

Next week:

Lectures posted to Blackboard

**NEXT WEEK:
CLASSES ARE PRE-RECORDED**



PHYSICS 101 - HONORS

Lecture 43 11/17/23

Simple Harmonic Motion (slide 3)

Recall that SHM is defined by the (2nd order homogeneous ordinary differential) equation

$$\ddot{x} + \omega^2 x = 0$$

And the most general solution can be written as

$$x(t) = A \cos(\omega t + \phi) \quad \leftarrow \text{generalises } x(t) = e^{\pm i\omega t}$$

Note: Euler's formula tells us

$$e^{i\omega t} = \cos(\omega t) + i\sin(\omega t)$$

$$e^{-i\omega t} = \cos(\omega t) - i\sin(\omega t)$$

These can be solved to express $\cos(\omega t)$ and $\sin(\omega t)$ as

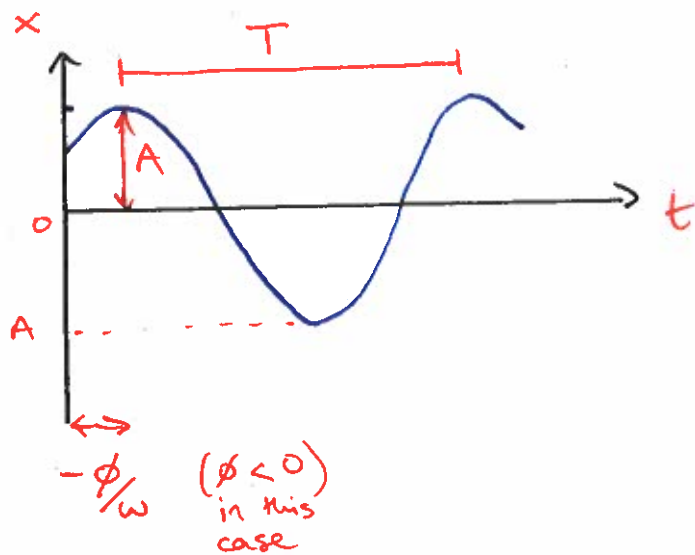
$$\cos(\omega t) = \frac{e^{i\omega t} + e^{-i\omega t}}{2}$$

$$\sin(\omega t) = \frac{e^{i\omega t} - e^{-i\omega t}}{2i}$$

There is a theorem that says that if two functions are solutions of an ODE, then so are sums and multiples of these functions. Thus, if $e^{+i\omega t}$ and $e^{-i\omega t}$ both satisfy $\ddot{x} + \omega^2 x = 0$, then so does $\frac{e^{i\omega t} + e^{-i\omega t}}{2} = \cos(\omega t)$.

↑
which is how we obtain our general solution

Our solution can be drawn as



$$x(t) = A \cos(\omega t + \phi)$$

↑ amplitude
 ↑ phase

↓ angular frequency

Amplitude - minimum/maximum value of $x(t)$

Frequency - $f = \frac{\omega}{2\pi}$ - number of oscillations per second

$$f = \frac{1}{T}$$

Period - $T = \frac{1}{f} = \frac{2\pi}{\omega}$ - time take for one oscillation

Phase - "offset" where crest or trough occurs

e.g. if $\phi = 0$ the $x(t) = A \cos(\omega t) = \underset{\substack{\uparrow \\ \text{crest}}}{A}$ at $t=0$

Velocity - $v = \frac{dx}{dt} = -A\omega \sin(\omega t + \phi)$ \leftarrow varies periodically!

Acceleration - $a = \frac{d^2x}{dt^2} = -A\omega^2 \cos(\omega t + \phi)$ \leftarrow

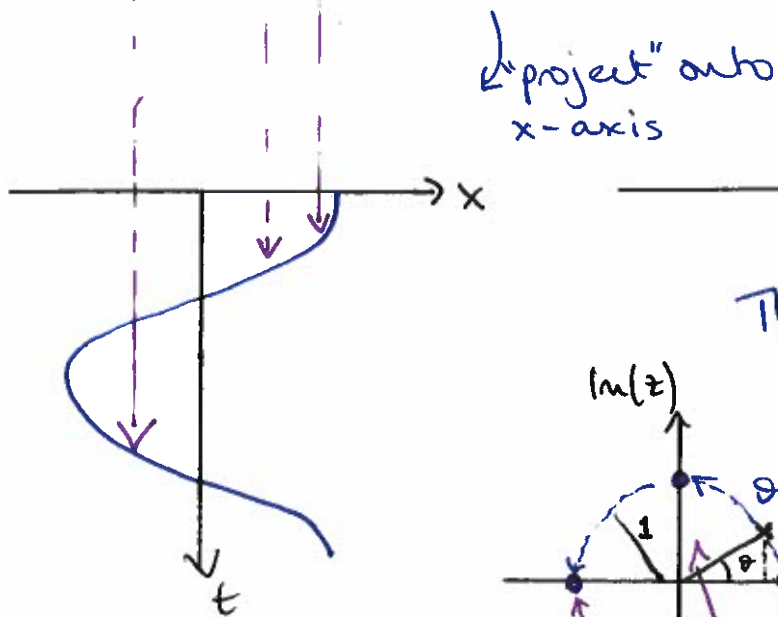
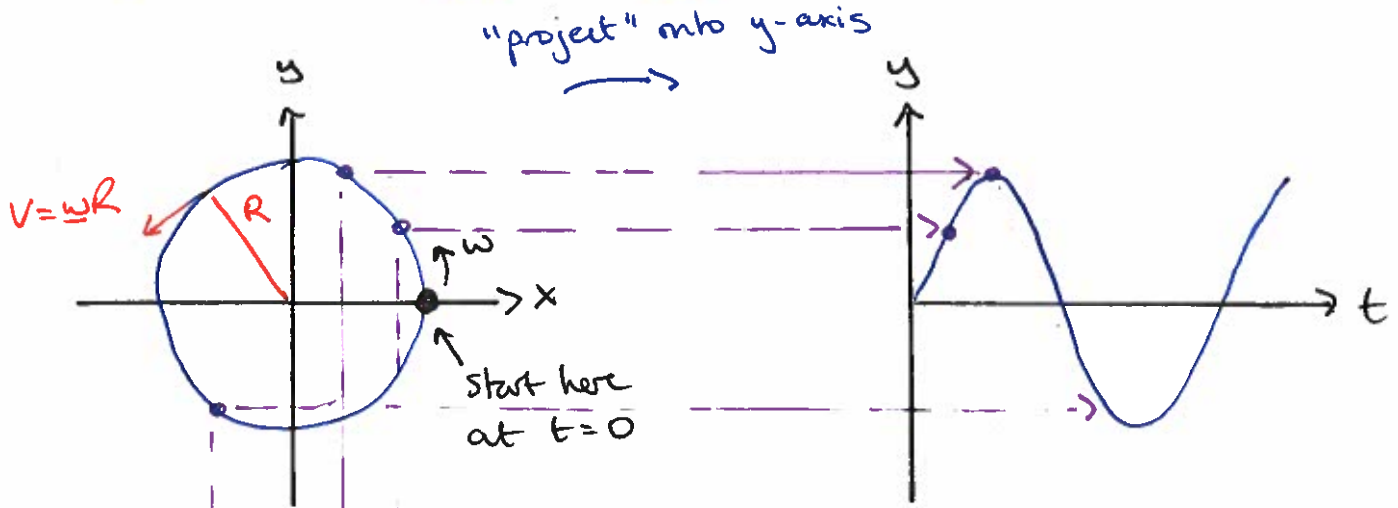
Max velocity $|v_{\max}| = A\omega = \sqrt{\frac{k}{m}} A$

Max acceleration $|a_{\max}| = A\omega^2$

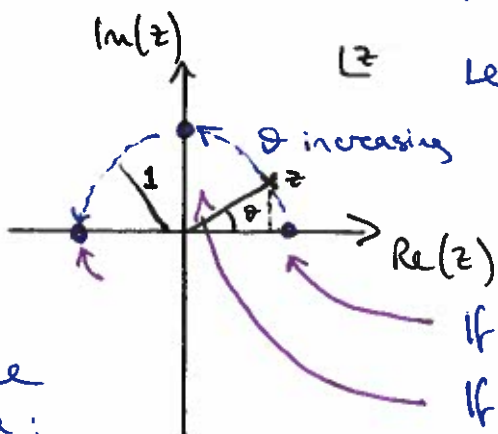
Uniform circular motion (slide 4)

We can relate SHM to circular motion!

Plot the x position of a particle undergoing circular motion and it traces out a cosine (or sine) wave = SHM!



This helps us visualise $e^{i\theta}$!



If $\theta = 0$ then $z = 1$

If $\theta = \frac{\pi}{2}$ then $z = i$

If $\theta = \pi$ then $z = -1$

Notice these values make sense in Euler's formula:

$$e^{i \cdot 0} = \cos(0) + i \sin(0) = 1 + i \cdot 0 = 1$$

$$e^{i \cdot \frac{\pi}{2}} = \cos\left(\frac{\pi}{2}\right) + i \sin\left(\frac{\pi}{2}\right) = 0 + i \cdot 1 = i$$

$$e^{i\pi} = \cos(\pi) + i \sin(\pi) = -1 + i \cdot 0 = -1$$

We can also use trig to understand the real and imaginary parts of z ...

eg $\text{Re}(z) = 1 \cdot \cos \theta = \cos \theta$ ✓

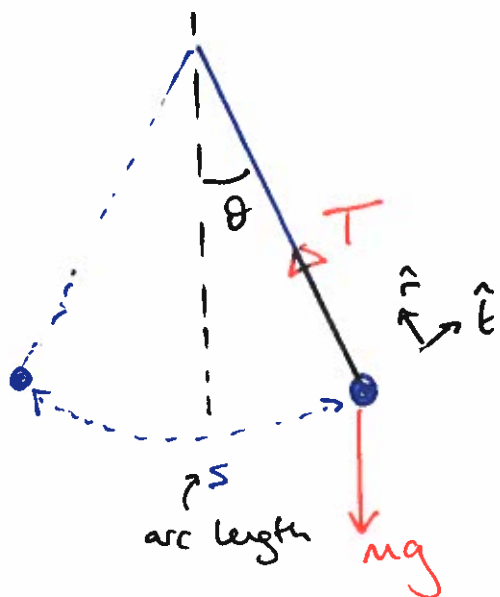
Actually, any "well-behaved" function can be written as an infinite sum of sines and cosines

$$f(x) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} a_n \cos(nx) + \sum_{n=1}^{\infty} b_n \sin(nx)$$

called the Fourier series of a function

The essence of this is that you can break down complicated problems into the sum of a bunch of harmonic oscillators of different frequencies (and amplitudes).

Simple pendulum example (slide 4)



$\vec{T} = T\hat{r}$ and $\vec{F}_g = -mg\cos\theta\hat{r} - mg\sin\theta\hat{t}$
are the only forces acting on the pendulum

Newton's second law tells us

$$\vec{F}_{\text{net}} = m\vec{a}$$

$$\Rightarrow \vec{T} + \vec{F}_g = m\vec{a} \quad \text{or} \quad T\hat{r} + (-mg\cos\theta\hat{r} - mg\sin\theta\hat{t}) = m\vec{a}$$

The acceleration in this case is $\vec{a} = a_r\hat{r} + a_t\hat{t}$

⇒ in radial direction:

$$T - mg \cos \vartheta = m a_r = \frac{m v^2}{r}$$

\uparrow
 $a_r = a_c = \frac{m v^2}{r}$

and in the tangential direction

$$-mg \sin \vartheta = m a_t \Rightarrow a_t = -g \sin \vartheta$$

But we know that

$$a_t = \frac{d^2 s}{dt^2} \quad \text{and since } s = L \vartheta \Rightarrow a_t = \frac{d^2}{dt^2} (L \vartheta) = L \frac{d^2 \vartheta}{dt^2}$$

So we have

$$L \frac{d^2 \vartheta}{dt^2} = -g \sin \vartheta \Rightarrow \frac{d^2 \vartheta}{dt^2} = -\frac{g}{L} \sin \vartheta$$

Now introduce $\omega^2 \equiv \frac{g}{L} \Rightarrow \frac{d^2 \vartheta}{dt^2} = -\omega^2 \sin \vartheta$

valid for any
angle ϑ

If we use the Taylor series

$$\sin \vartheta \approx \vartheta - \frac{1}{3!} \vartheta^3 + \frac{1}{5!} \vartheta^5 + \dots$$

then for small angles we can approximate $\sin \vartheta \approx \vartheta$

$$\Rightarrow \boxed{\frac{d^2 \vartheta}{dt^2} = -\omega^2 \vartheta}$$

← solution is $\vartheta(t) = A \cos(\omega t + \phi)$
with $\omega = \sqrt{\frac{g}{L}}$ the

angular frequency
simple harmonic motion!